

A Holistic View on NDT Reliability: Multi-Parameter-POD and Human Factor Influences within the Modular Reliability Approach

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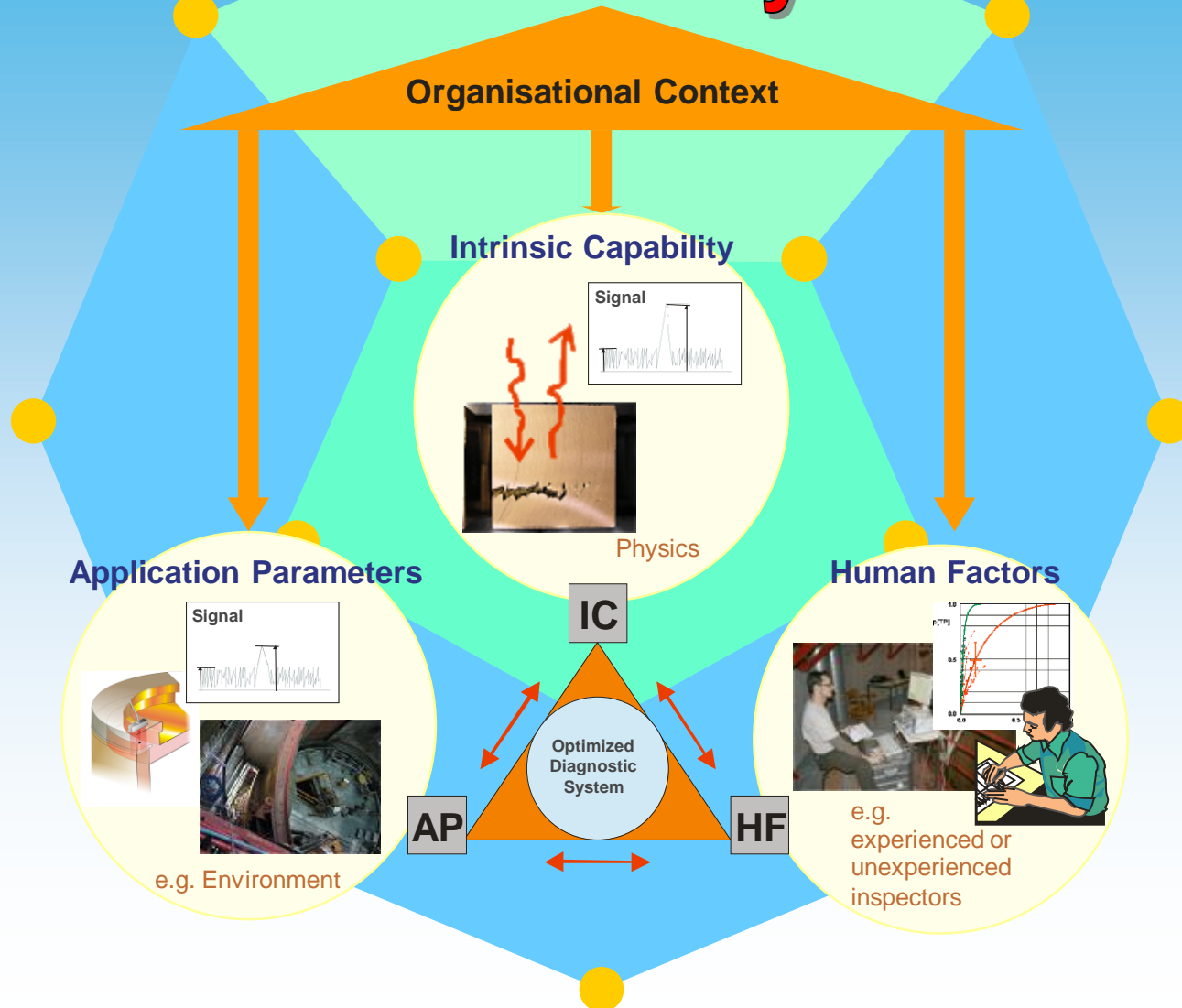
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Ulf Ronneteg, SKB, Oskarshamn, Sweden

Jorma Pitkänen, Posiva Oy, Eurajoki, Finland

Modular Reliability Model



Progress in Methods for

- ➡ 1. **Intrinsic Capability: Physics and technical influences**
- ➡ 2. **Application Parameters: Environment of the experiment**
- ➡ 3. **Human Factors: In calibration, set up and evaluation and decision making as well as in the organizational context**
- ➡ 4. **Organizational Context: Business-, Technical-, Information Process**

Contents

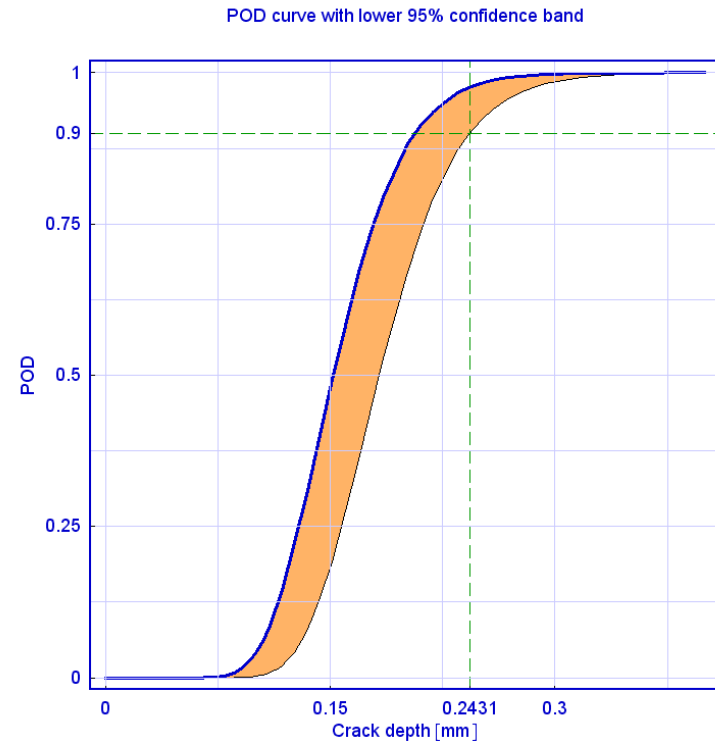
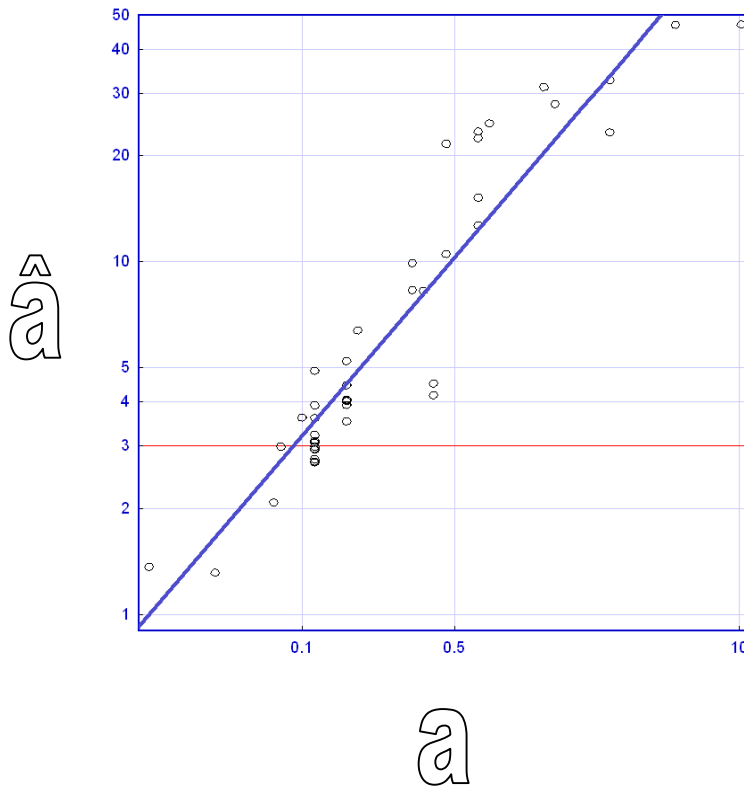
- ➡ 1. Intrinsic Capability
- ➡ 2. Application Parameters
- ➡ 3. Human Factors

Probability of Detection (POD)

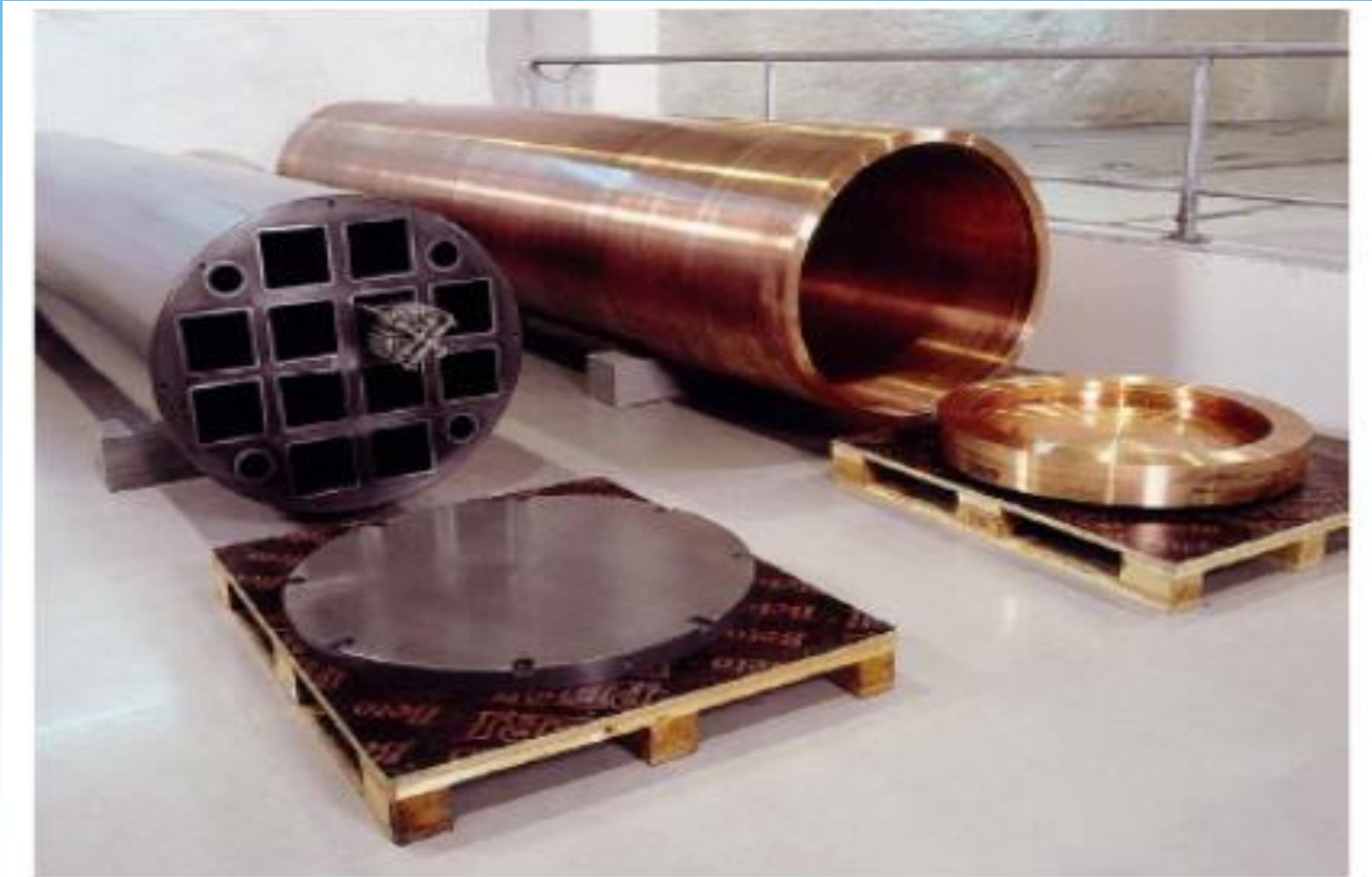
– \hat{a} vs. a approach – for realistic testing conditions

We need multi-parameter „ a “ (depth, size, orientation, roughness ...)

And data-field „ \hat{a} “ (more than a maximum) for real industrial appl.

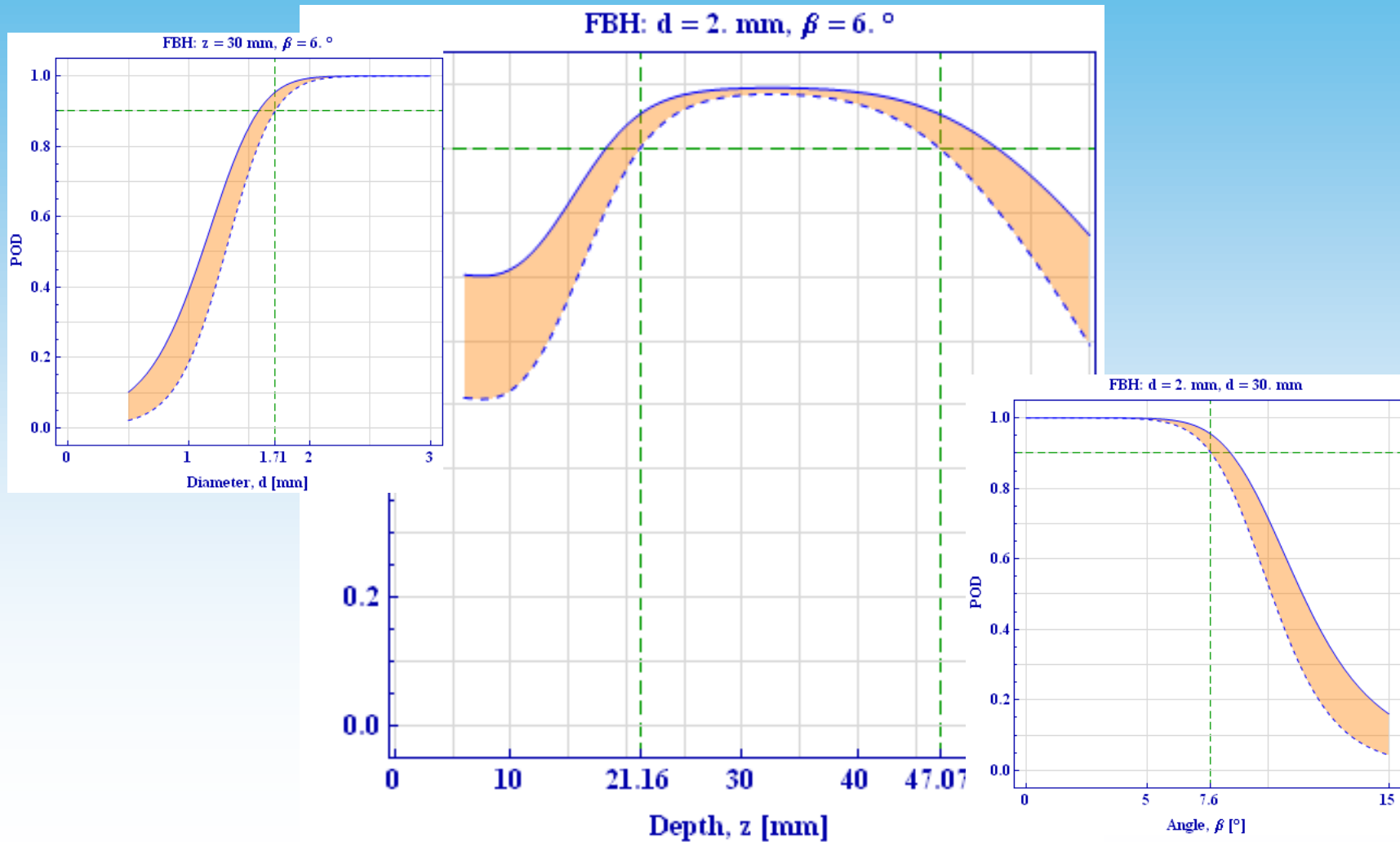


Copper Canisters for Spent Nuclear Fuel SKB

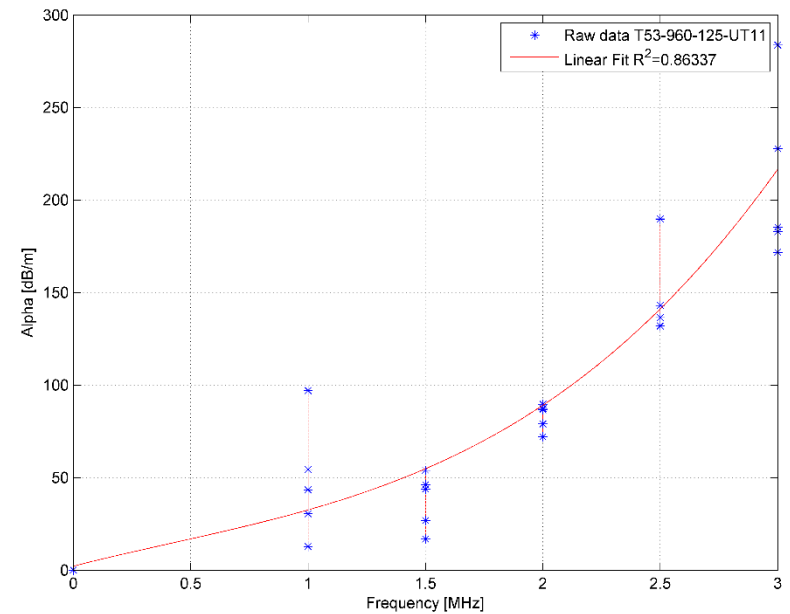
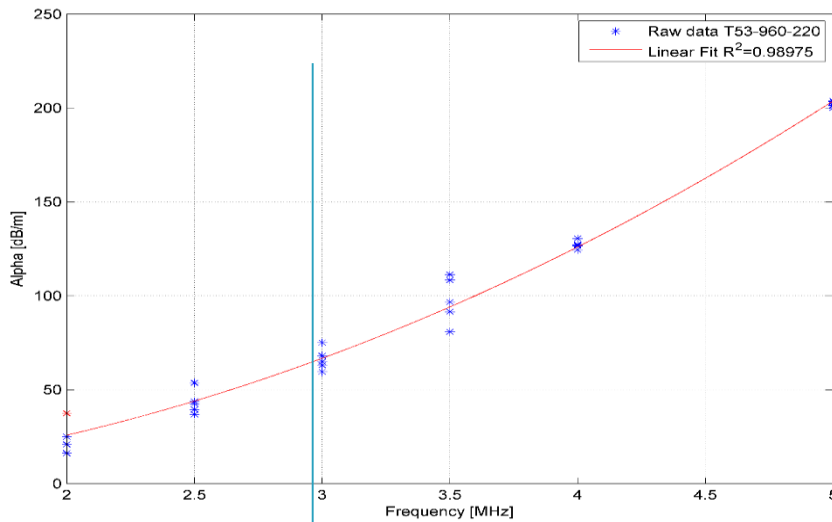
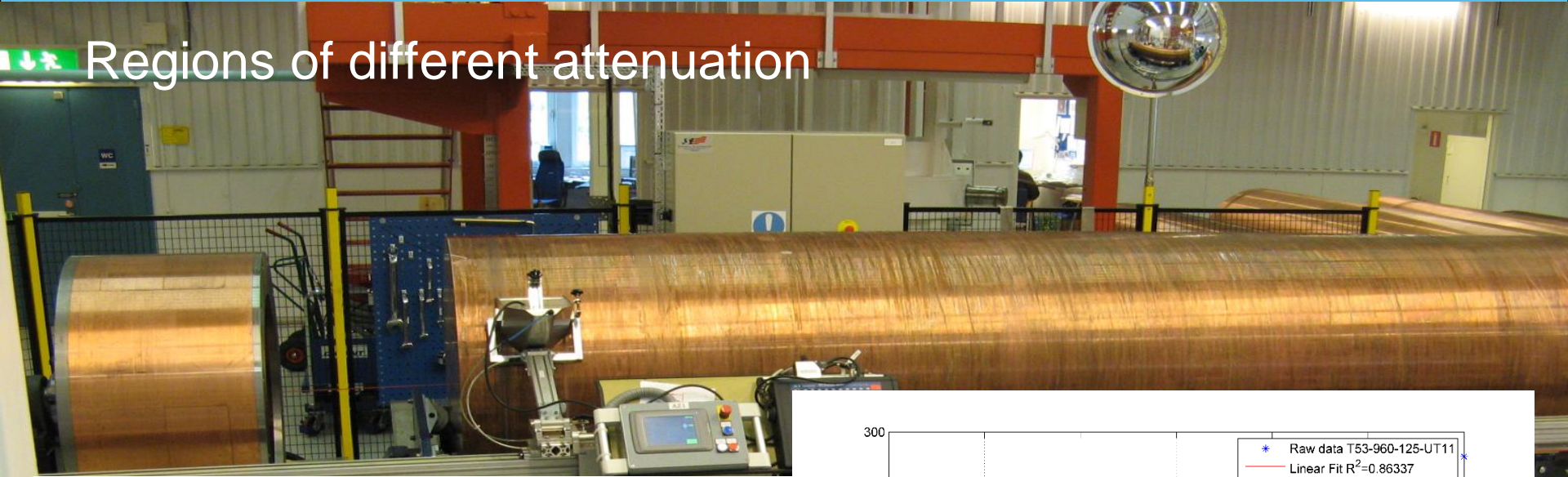


MP-POD as function of diameter, depth, angle

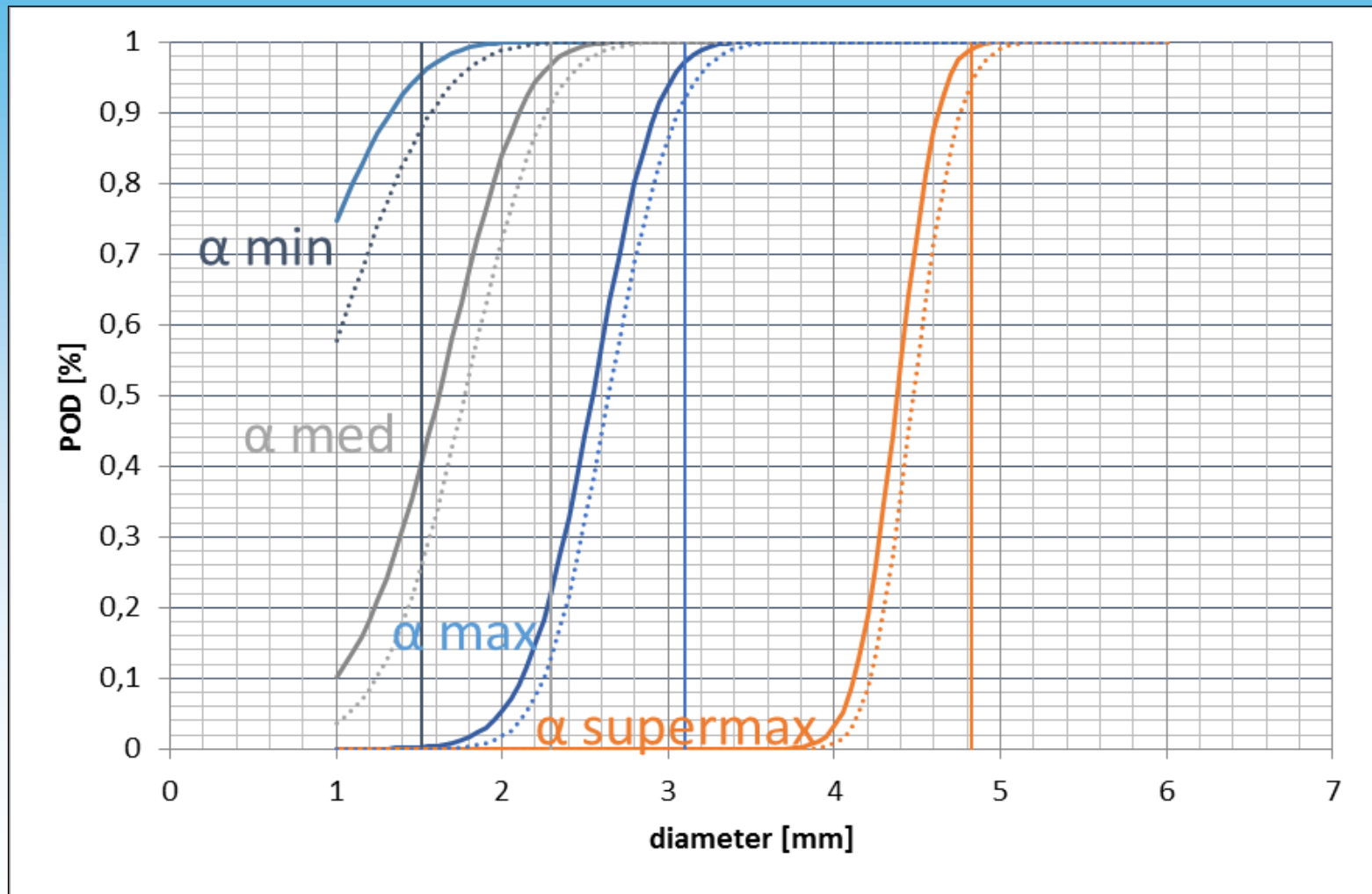
Mato Pavlovic (UT testing of copper canisters)



Regions of different attenuation



MP-POD for Copper with different UT attenuation

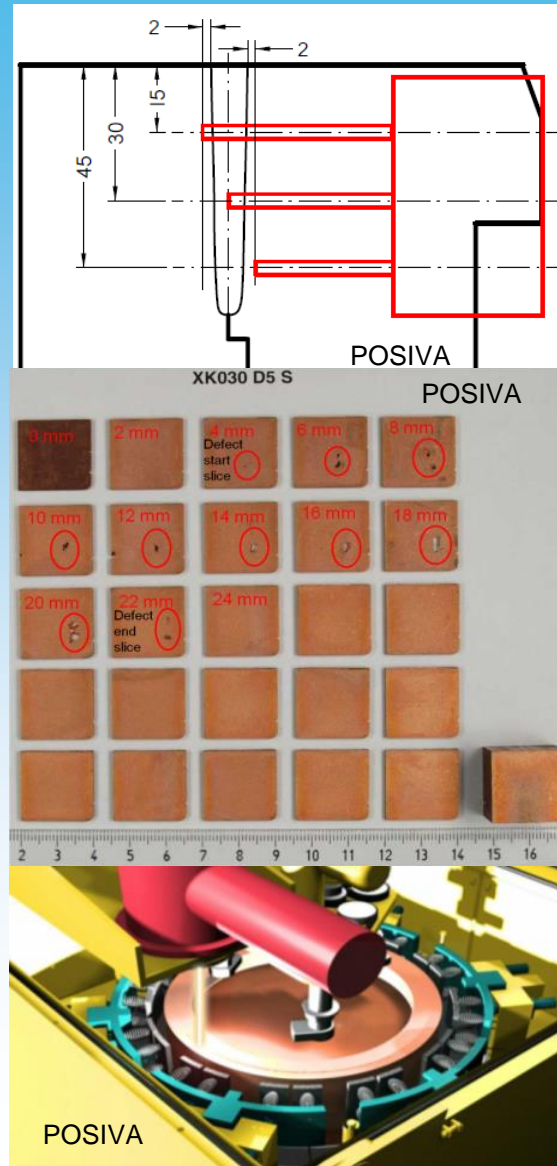


From artificial to real flaws: Three-Step Testing

Artificial defects –
According to the EN &
ASTM
Standards

Realistic welding
defects
(in this work: = real
defects)

Production of the
disposal canisters for
the use in the final
disposal (after 2020)



The POD of artificial defects:

-evaluate the measurement process / the application factor
=> POD describes the limits with an ideal defect behavior.

The POD of real defects:

-evaluate of the interaction with complex defects
=> necessary for an “Overall POD”.

Bayesian Approach

D. Kanzler

Contents

- ➡ 1. Intrinsic Capability
- ➡ 2. Application Parameters
- ➡ 3. **Human Factors embedded in an industrial application area**

Statistical Evaluation of Manual UT of Railway Hollow Wheel Axles

- Artificial and real defects at different positions (shaft, seat, transition region (unknown size and angle, ~ 2 mm notch)
- Defined Technique UT 5 MHz 45°, 70° inwards, outwards
- UT inspectors during education examination (first and refresher and 1 extra round robin)

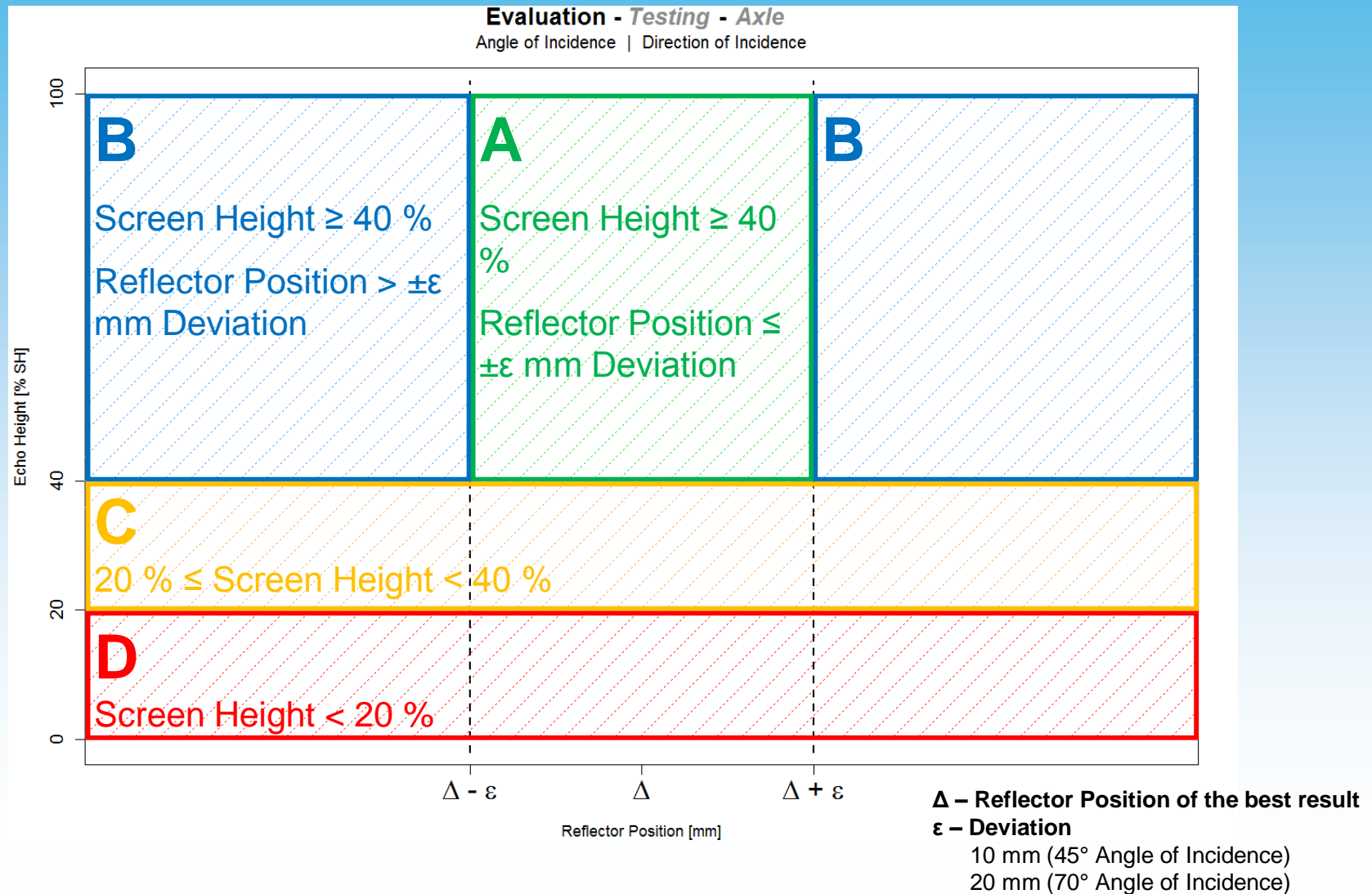
Overview of the data

Number		Round Robin Test	Refresher Examination	part. Mechanized Testing	First Examination
Axles		1	23	1	13
UT-Probes	45°	10	24	2	9
	70°	7	10	-	1
Protocols		26	599	236	18
Measurement Values	<u>total</u>	272	3477	(2088)	105
	Calibration Reflector / Geometrical Contour Echo	97	1786	-	38
	not usable*	63/6	620/292	39/39	44/1
	relevant*	112/169	1071/1399	197/197	23/66

* first value: Evaluation Echo Height / DeltaPhi; second value: Evaluation Echo Height / Reflector position

Stand: 22.05.2014

Graphical Illustrations – Echo Height [%SH] / Reflector Position [mm]

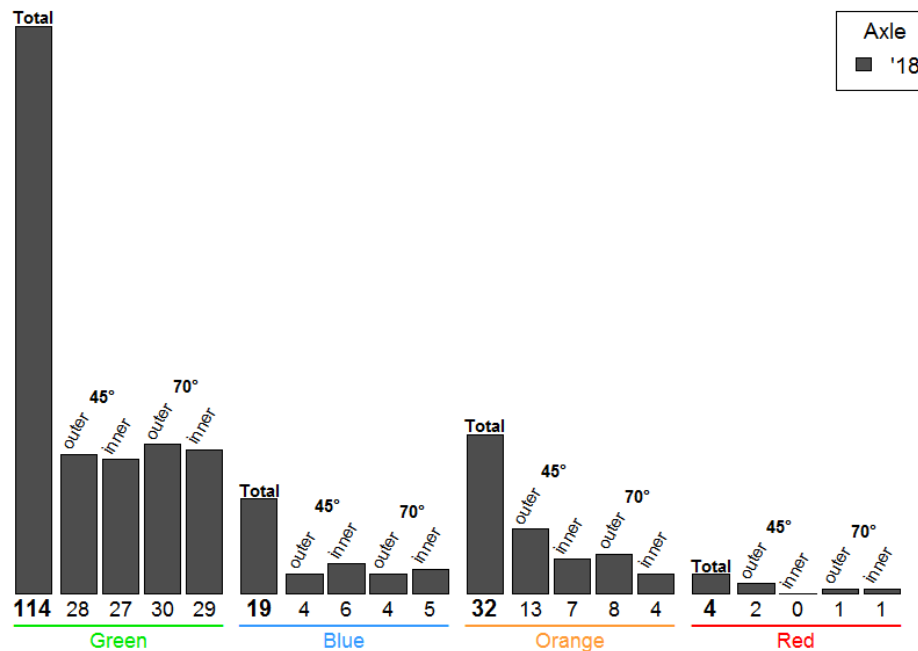


Overview – Round Robin Test

Reflector Position $\leq \pm 10/20$ mm Deviation

70°, inner	74	13	10	3
70°, outer	70	9	19	2
45°, inner	68	15	17	
45°, outer	60	8	28	4
Total	68	11	19	2

Relative Frequency of Occurrence [%]



Absolute Frequency of Occurrence [-]

Axle
■ '18'

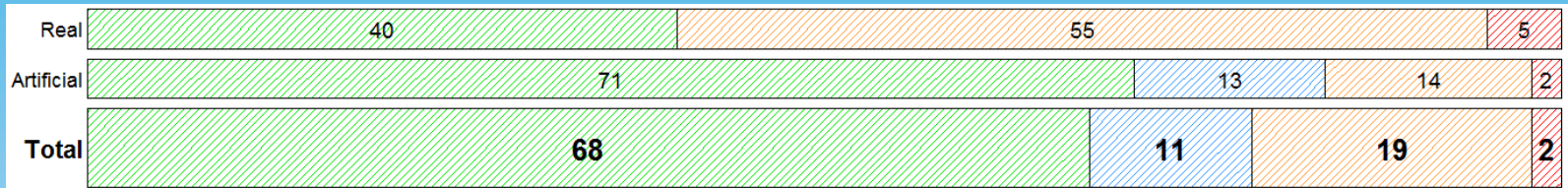
- **Green**
Screen Height $\geq 40\%$
Refl. Position $\leq \pm 10/20\text{mm}$ (45°/70°)
- **Blue**
Screen Height $\geq 40\%$
Refl. Position $> \pm 10/20\text{mm}$ (45°/70°)
- **Orange**
Screen Height $< 40\%$
Screen Height $\geq 20\%$
- **Red**
Screen Height $< 20\%$

Number of Measurement Values

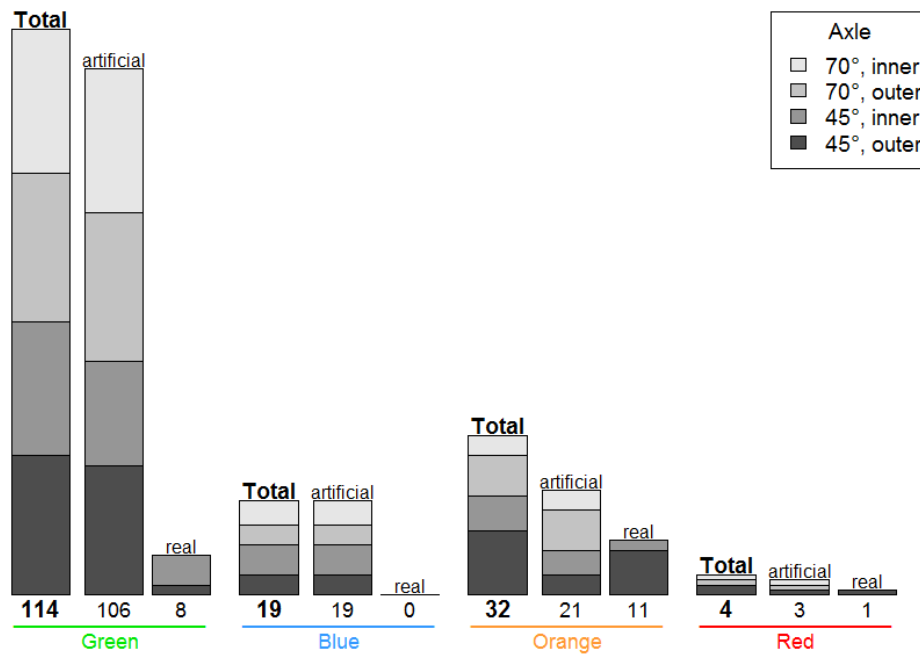
45°, outer	47
45°, inner	40
70°, outer	43
70°, inner	39
Total Number	169

Comparison Artificial/real Defects – Round Robin Test

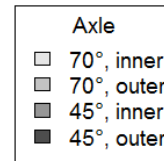
Reflector Position $\leq \pm 10/20$ mm Deviation



Relative Frequency of Occurrence [%]



Absolute Frequency of Occurrence [-]



- Green**
Screen Height $\geq 40\%$
Refl. Position $\leq \pm 10/20\text{mm}$ ($45^\circ/70^\circ$)
- Blue**
Screen Height $\geq 40\%$
Refl. Position $> \pm 10/20\text{mm}$ ($45^\circ/70^\circ$)
- Orange**
Screen Height $< 40\%$
Screen Height $\geq 20\%$
- Red**
Screen Height $< 20\%$

Number of Measurement Values

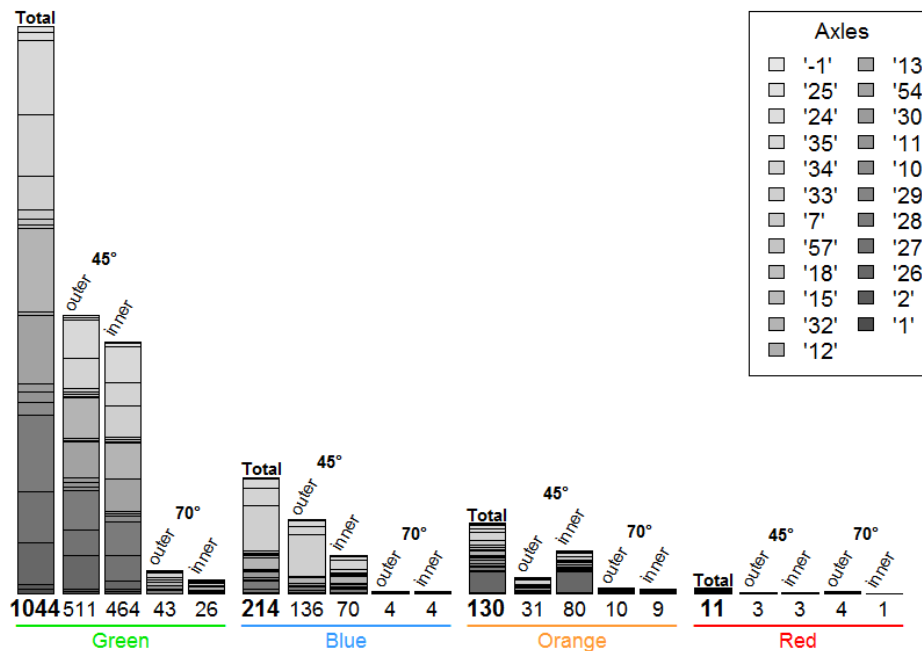
Artificial Defect	149
Real Defect	20
Total Number	169

Overview – Refresher Course Examination

Reflector Position $\leq \pm 10/20$ mm Deviation

70°, inner	65	10	23	2
70°, outer	70	7	16	7
45°, inner	75	11	13	1
45°, outer	75	20	5	
Total	75	15	9	1

Relative Frequency of Occurrence [%]



Absolute Frequency of Occurrence [-]

Axles	
'-1'	'13'
'25'	'54'
'24'	'30'
'35'	'11'
'34'	'10'
'33'	'29'
'7'	'28'
'57'	'27'
'18'	'26'
'15'	'2'
'32'	'1'
'12'	

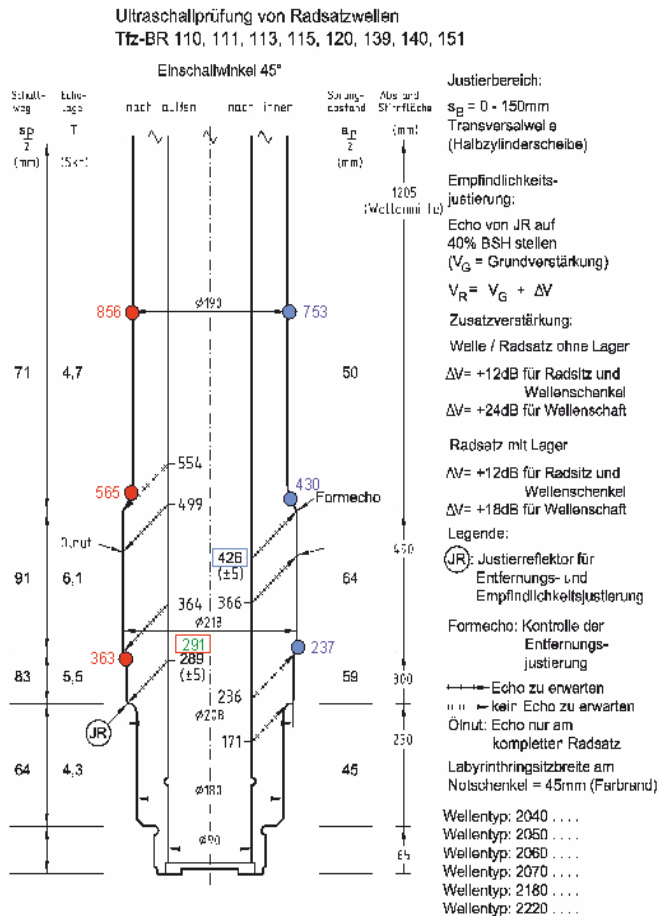
- **Green**
Screen Height $\geq 40\%$
Refl. Position $\leq \pm 10/20\text{mm}$ (45°/70°)
- **Blue**
Screen Height $\geq 40\%$
Refl. Position $> \pm 10/20\text{mm}$ (45°/70°)
- **Orange**
Screen Height $< 40\%$
Screen Height $\geq 20\%$
- **Red**
Screen Height $< 20\%$

Number of Measurement Values

45°, outer	681
45°, inner	617
70°, outer	61
70°, inner	40
Total Number	1399

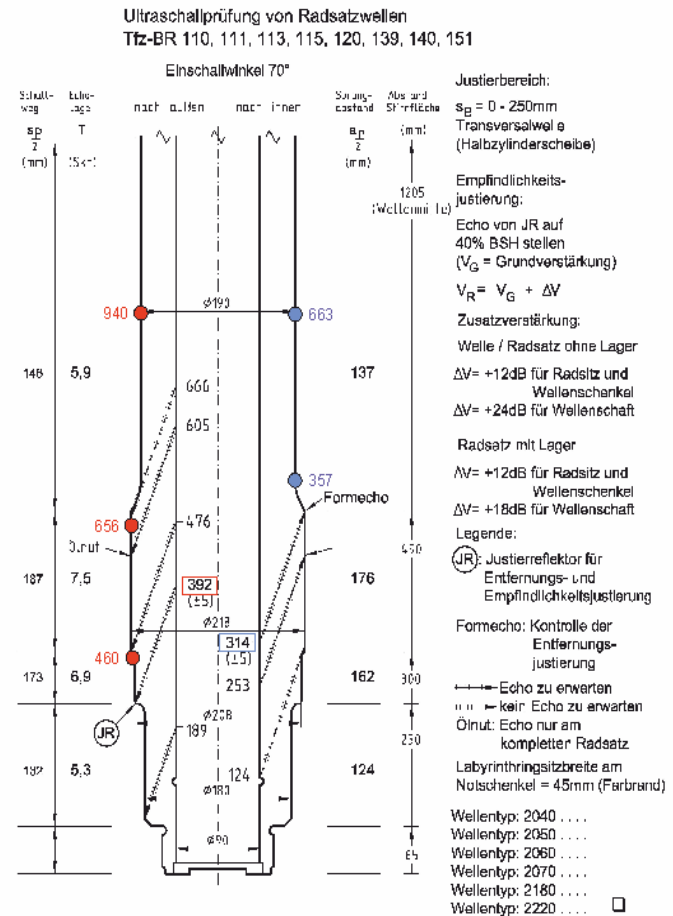
Axles for Round Robin Test with defects

Radsatzwelle ,18'



807.8010 Ultraschallprüfung von Radsatzwellen Seite 1/7
 Tfz-BR 110, 111, 113, 115, 120, 139, 140, 151 (folgt ein folgendes Muster) A/ 4-80
 Farband: v17 34 F. (07) 5985 12.03.05

Radsatzwelle ,18'



807.8010 Seite 2/7
 12.03.05

4781232P

Round Robin Test – Total-POD – 3 Defects in 1 axle – 267 measurements

$$POD_{HIT}^{Total} = \left(1 - \left(1 - POD_{HIT}^{45^\circ, outer}\right) \times \left(1 - POD_{HIT}^{45^\circ, inner}\right) \times \left(1 - POD_{HIT}^{70^\circ, outer}\right) \times \left(1 - POD_{HIT}^{70^\circ, inner}\right)\right)$$

Bold → Transition region
Italic → Seat
 Normal → Shaft

Number of Axle Protocols	Defect Position [mm]	<i>POD</i> _{HIT} ^{45°, outer}	<i>POD</i> _{HIT} ^{45°, inner}	<i>POD</i> _{HIT} ^{70°, outer}	<i>POD</i> _{HIT} ^{70°, inner}	<i>POD</i> _{HIT} ^{Total}
'18'	299	0,42	0,21	0,28	-	0,67
97	500*	0,50	0,33	0,92	0,79	0,99
97	803	0,92	1,00	0,36	0,79	1,00

* Real crack

Position bold means „transition“ between shaft and seat

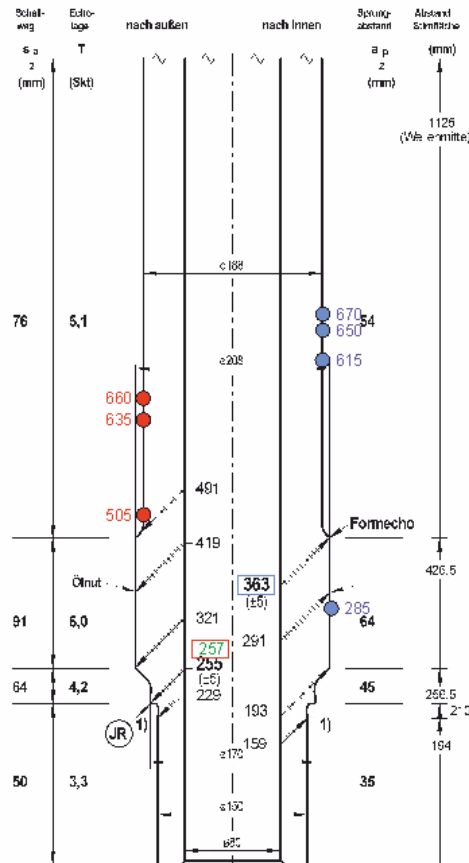
The artificial defect in the shaft at 803 mm is found with 100 % POD while the real defect at 500 mm is found with 99 % POD and the artificial defect at 299 mm with 67 % The latter are beta situated in the transition region but right have different sizes.

Axles with defects in the transition region, seat and shaft – more than 1000 refresher measurements (22 axles, 65 defects)

Radsatzwelle ,12'

Ultraschallprüfung von Treibradsatzwellen
ET-BR 401, 402 (ICE 1 u. 2)

Einschallwinkel 45°



907.9D41

Ultraschallprüfung von Radsatzwellen
ET-BR 401, 402 (fotokopierfähiges Muster) A4 4a-80
Fachschr. 1.12.04 Pl. 1937 0815

21.2010

Justierbereich:

$s_B = 0 - 190\text{mm}$
Transversalwelle
(Halbzylinderscheibe)

Empfindlichkeitsjustierung:

Echo von JR auf
40% BSH stellen;
(V_G = Grundverstärkung)

$$V_R = V_G + \Delta V$$

Zusatzverstärkung:

Welle/Radsatz ohne Lager
 $\Delta V = +12\text{dB}$ für Radsatz und
Wellenschenkel
 $\Delta V = +24\text{dB}$ für Wellenschaft
ab 426,5 mm Länge

gefügter / eingebauter Radsatz
Radsatz mit Lager

$\Delta V = +12\text{dB}$ für Radsatz und
Wellenschenkel
 $\Delta V = +18\text{dB}$ für Wellenschaft
ab 426,5 mm Länge

Legende:

JR: Justierreflektor für
Entfernungs- und
EmpfindlichkeitsEinstellung

Formecho: Kontrolle der
Entfernung

--- Echo zu erwarten
- - - kein Echo zu erwarten

Ölnut: Echo nur am
kompletten Radsatz

Labyrinthingsitzbreite am
Notschenkel = 10 mm (Farbrand)

1) Anzeige aus Ende neuer
Spritzschicht ($\pm 2\text{mm}$)

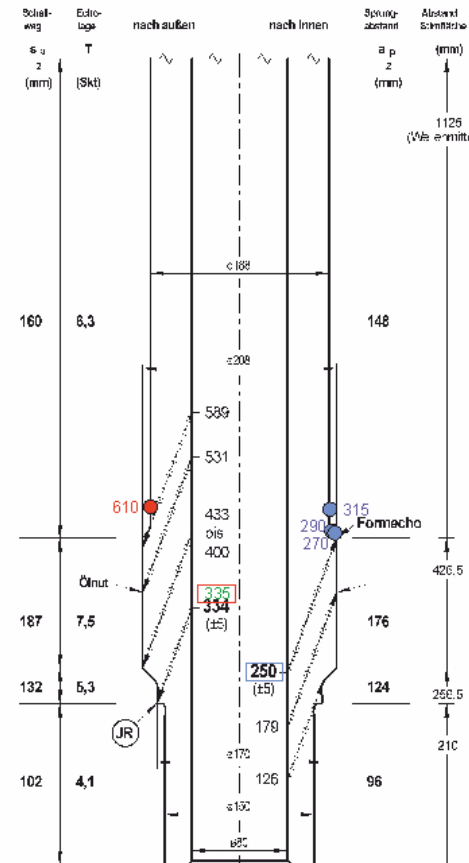
Wellentyp: 2510

Seite 1/5

Radsatzwelle ,12'

Ultraschallprüfung von Treibradsatzwellen
ET-BR 401, 402 (ICE 1 u.2)

Einschallwinkel 70°



907.9D41

Ultraschallprüfung von Radsatzwellen
ET-BR 401, 402 (fotokopierfähiges Muster) A4 4a-80
Fachschr. 1.12.04 Pl. 1937 0815

21.2010

Justierbereich:

$s_B = 0 - 250\text{mm}$
Transversalwelle
(Halbzylinderscheibe)

Empfindlichkeitsjustierung:

Echo von JR auf
40% BSH stellen;
(V_G = Grundverstärkung)

$$V_R = V_G + \Delta V$$

Zusatzverstärkung:

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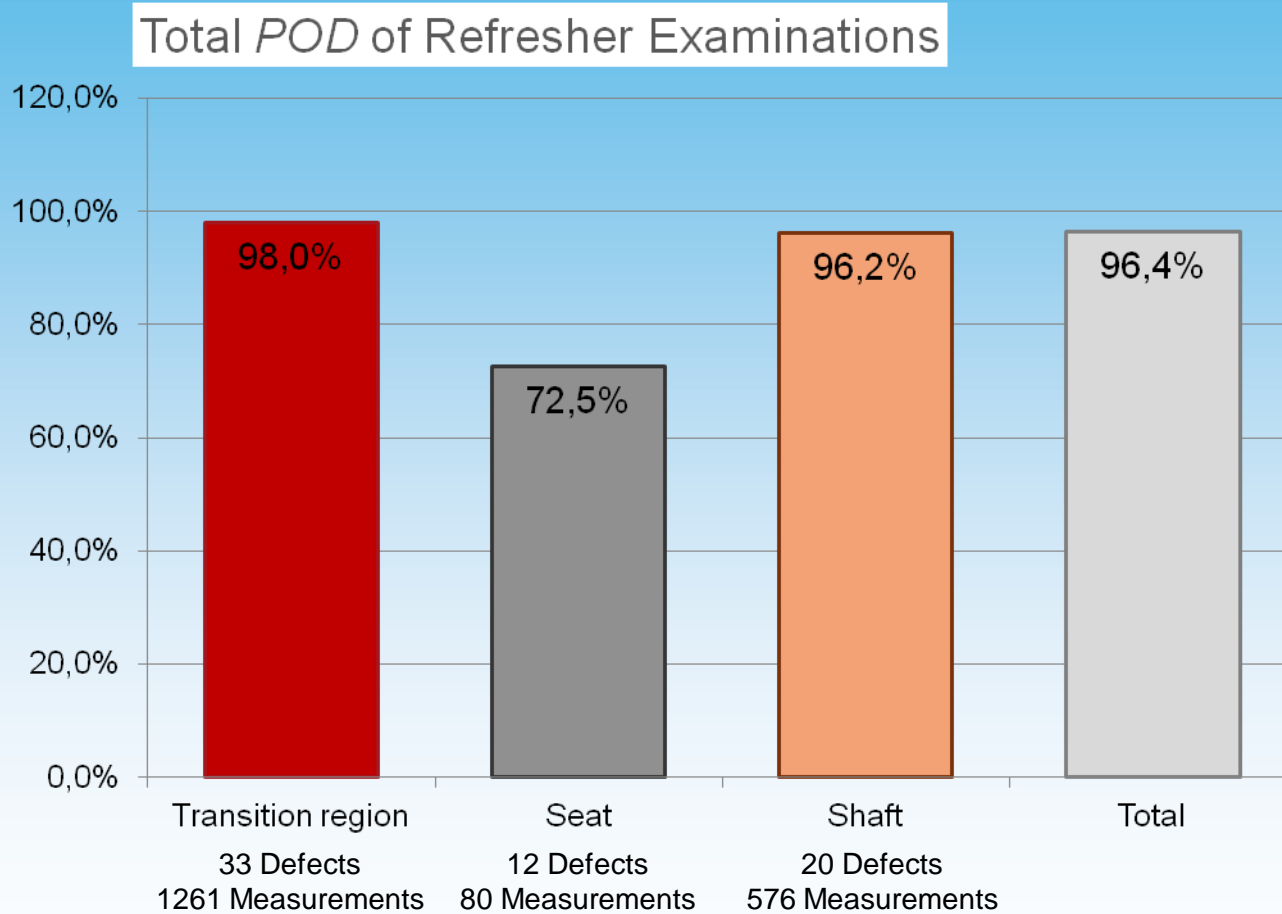
Labyrinthingsitzbreite am
Notschenkel = 10 mm (Farbrand)

Wellentyp: 2510

Seite 2/5

01.2010

Refresher Examination – Total-POD



Total number of defects: **65**
Total number of measurements: **1917**

Human factors

- ➔ Investigations by our working psychologist Marija Bertovic



BAM

Bundesanstalt für
Materialforschung
und -prüfung

8.3 *Radiologische
Verfahren*

Zuverlässigkeit zerstörungsfreier Prüfsysteme



DEUTSCHE
GESELLSCHAFT FÜR
ZERSTÖRUNGSFREIE
PRÜFUNG E.V.

Research questions

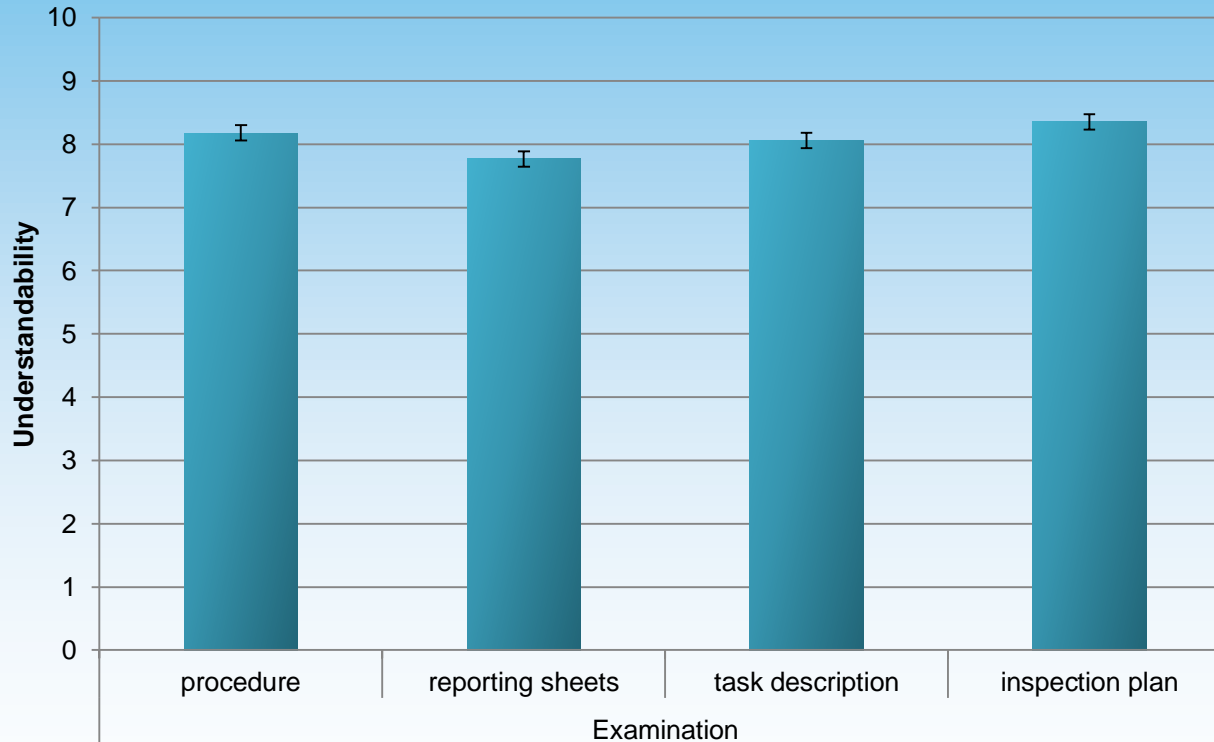
- ➡ There is a variability in the inspection results!
 - Which factors lead to variability?
 - How can these factors be controlled?
 - How can the reliability be increased?
- ➡ 1. step – questionnaire:



M. Bertovic

Preliminary results (N=18)

➡ During examination



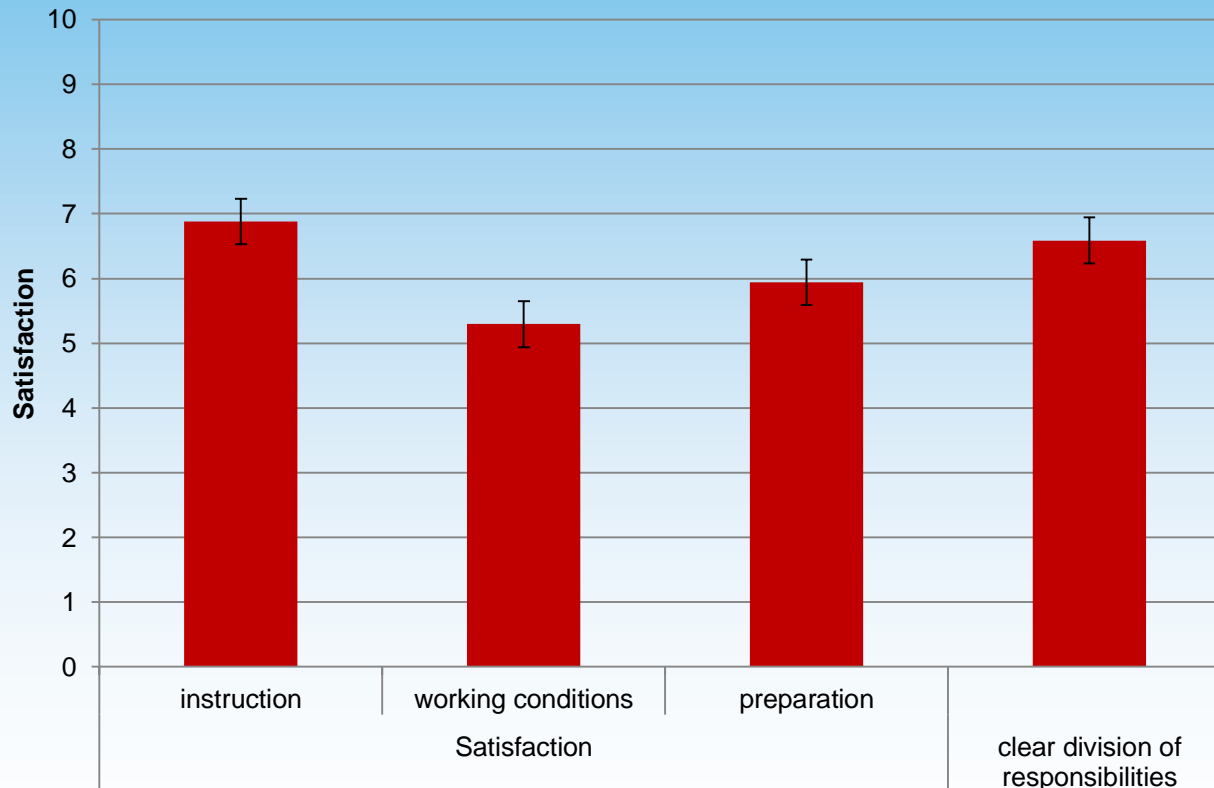
How understandable is the documentation?

- a) Inspection procedure
- b) Reporting sheets
- c) Task description
- d) Inspection plan

M. Bertovic

Preliminary results (N=18)

➔ In the field



How satisfied are you with :

- a) The quality of the **instruction** through the supervisors (e.g. explanations, task description)
- b) **Working conditions** in the field (e.g. cleanliness, temperature, noise, access)
- c) **Inspection preparation** (e.g. preparation of the components, documentation, time, coordination)

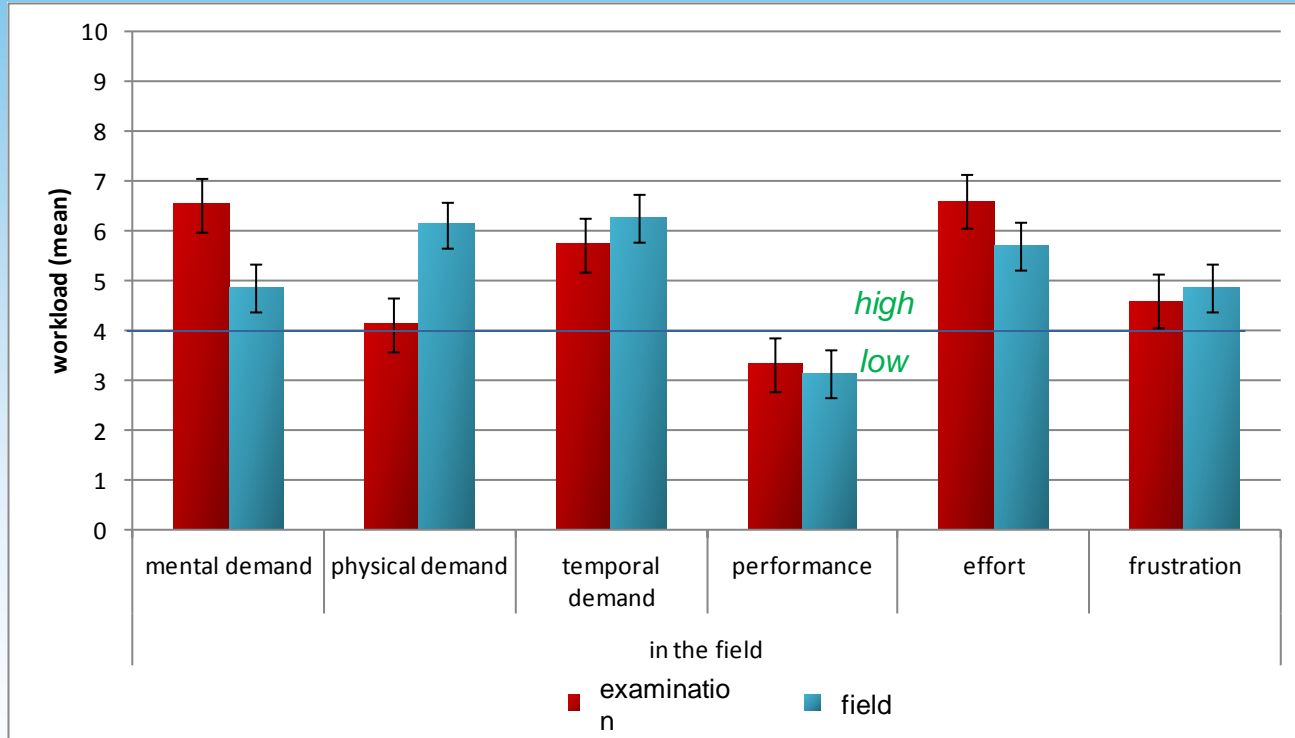
How clear is

- a) The division of **responsibilities** (e.g. inspector, supervisor, management)

M. Bertovic

Preliminary results (N=18)

➔ During the examination and in the field



MENTAL WORKLOAD

Mental Demand

How much mental and perceptual activity was required (e.g. thinking, deciding, calculating, remembering, looking, searching, etc.)?

Physical Demand

How much physical activity was required (e.g. pushing, pulling, turning, controlling, activating, etc.)?

Temporal demand

How much time pressure did you feel due to the rate or pace at which the tasks or task elements occurred?

Performance

How satisfied were you with your performance in accomplishing these goals?

Effort

How hard did you have to work (mentally and physically) to accomplish your level of performance?

Frustration

How insecure, discouraged, irritated, stressed and annoyed did you feel during the task?

M. Bertovic

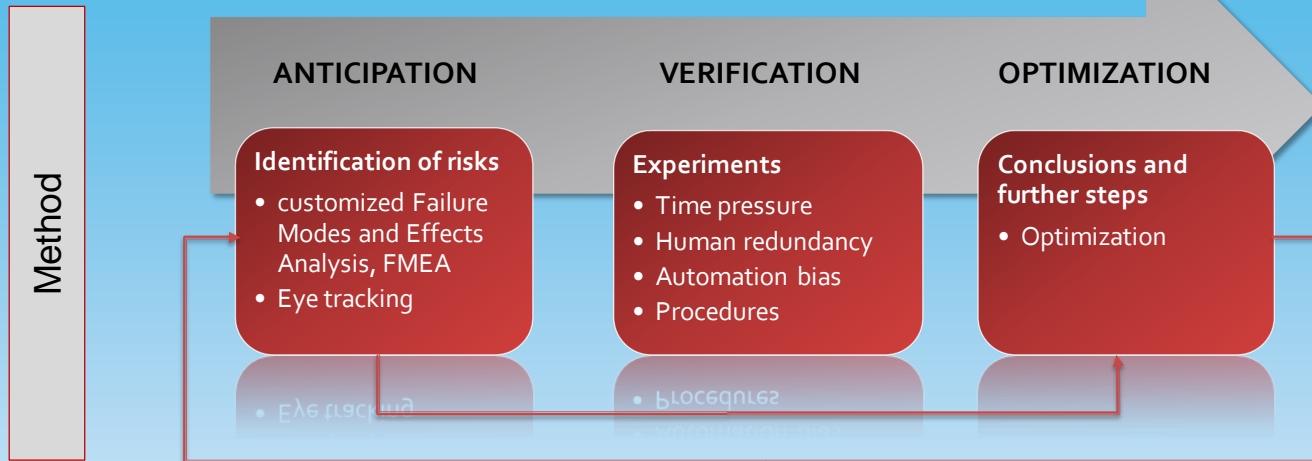
General Problems of HF in NDT

- Observation: variability in the inspection results
 - Source: human factor

- Problem: gap in knowledge
 - Variability attributed only to the inspector
 - ▶ other influences neglected or unknown (technology, team, organization, extra-organizational environment)
 - Manual vs. mechanized NDT
 - ▶ Mechanized NDT is seen as the solution for the „human factors problem“
 - Research in the field of NDT is missing!
 - Knowledge not reaching the end user
 - ▶ Bridge between engineering and psychology needed
 - Methodology how to address human factors in NDT unknown
 - Optimization methods
 - ▶ Missing or not implemented

M. Bertovic

Human factors approach

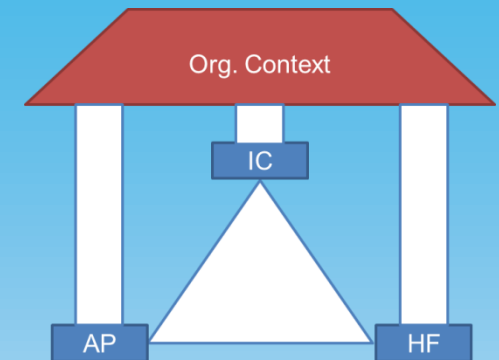


- Main conclusions**
- **FMEA:** There is a risk of failure in mechanised NDT
 - The risk arises not only from the inspector, but mainly from the technological shortcomings, organisation, characteristics of the task and the environment, human-human and human-automation interaction.
 - **Overtrust** in the reliability of the mechanised equipment or an automated software can lead to errors (compliance with the errors of the automation).
 - **Time pressure** has an effect on the inspection quality. **Organisation** even a more important one!
 - Only when inspectors work completely independently of each other can we profit from **human redundancy** (4-eye principle).
 - **Inspection procedures and instructions** need to be developed with the user using human factors principles to:
 - ensure **understanding** of the content, and
 - increase **usability** of the procedure.

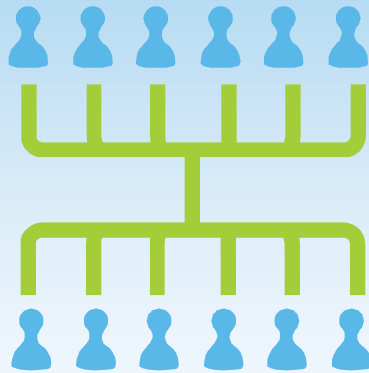
Progress in Methods for

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- ➡ 4. **Organizational Context: Business, technical and information process**

Organizational Context?



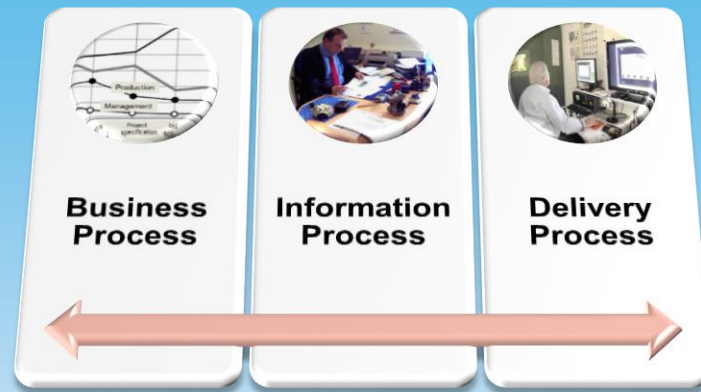
➔ Internal Organizational Factors



➔ External Organizational Factors

Ralf Holstein DGZfP

Human Factor and Organization



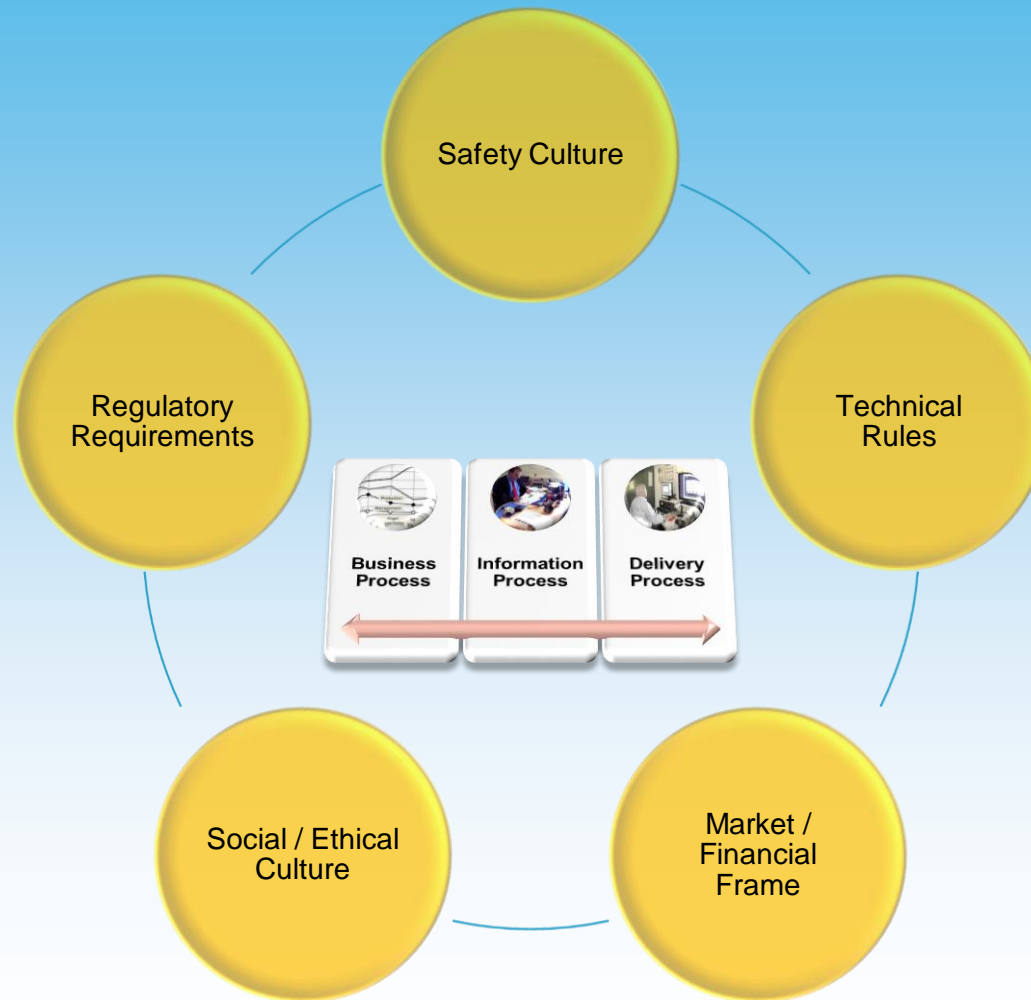
- ➡ All three processes influence operator performance
- ➡ Amount of information requires “*Information Management*”
- ➡ Communication Chain between

Customer - Contractor - Level III - Operator

should be carefully designed

Ralf Holstein DGZfP

Process Environment



Ralf Holstein DGZfP

Conclusions

- ➡ **ROC and POD** methods are adequate means measuring the reliability of NDE-systems for **high safety demands**
 - **But all influencing factors** needs to be known and controlled
 - POD of a component should be used as an **optimization tool (rather than final judgement)**
- ➡ **Human Factors in NDE → Complex Interactions**
 - Organizational context determines the way inspections are performed and therefore highly influences on the inspection quality in addition to individual capabilities.
- ➡ **NDE-reliability incl. HF-investigation → assist optimization**



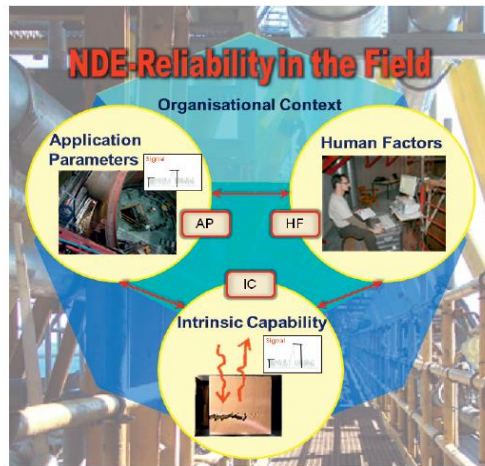
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GESELLSCHAFT FÜR
ZERSTÖRUNGSFREIE
PRÜFUNG E.V.



EF
European Federation for
Non-Destructive Testing
NDT

FIRST ANNOUNCEMENT AND
CALL FOR PAPERS

5th European-American Workshop
on Reliability of NDE



September 24 -26, 2013, Berlin, Germany

6th European American Workshop on Reliability of NDE

In connection with
QNDE 2015 - Minneapolis, USA
July 27-31st

Tutorial for POD basics

Lectures and posters:

Advanced Methods (MP-POD, MAPOD, BAYES)

Application in Industry

Reliability of SHM

Integrated Solutions

Human Factors

„Open space workshop“
on challenging topics

www.nde-reliability.de

christina.mueller@bam.de